#### Processes (Intro)

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# **Process: CPU Virtualization**

- Process = Program, instantiated
  - has memory, code, current state
- What kind of memory do we have?
  - registers + address space
- Let's do a hardware review

# Process API

- OSes will typically let you do the following with processes
  - create
  - destroy
  - wait
  - control (e.g., suspend) and notify
  - get status, info
- Demo process queries

# **Process Creation**

- Load code in memory
- Allocate *stack*, set initial args for main
- Set up *heap*
- Set up communication channels (open files)
- Call main

#### Example Modern Address Space (64-bit Linux)



# Loading



#### **Simplified Process States**



### **OS Structures**

- Structure holding all processes, per state
   how do you think this looks?
- PCB (Process Control Block) per process

#### xv6 Kernel Structures

```
// the registers xv6 will save and restore
// to stop and subsequently restart a process
struct context {
    int eip; // Index pointer register
    int esp; // Stack pointer register
   int ebx; // Called the base register
   int ecx; // Called the counter register
   int edx; // Called the data register
   int esi; // Source index register
   int edi; // Destination index register
   int ebp; // Stack base pointer register
};
// the different states a process can be in
enum proc state { UNUSED, EMBRYO, SLEEPING,
                 RUNNABLE, RUNNING, ZOMBIE };
```

#### xv6 Kernel Structures

```
// the information xv6 tracks about each process
// including its register context and state
struct proc {
   char *mem; // Start of process memory
                // Size of process memory
   uint sz;
   char *kstack; // Bottom of kernel stack
            // for this process
   enum proc state state; // Process state
   int pid;
                    // Process ID
   struct proc *parent; // Parent process
   void *chan; // If non-zero, sleeping on chan
   int killed;
                    // If non-zero, have been killed
   struct file *ofile[NOFILE]; // Open files
   struct inode *cwd; // Current directory
   struct context context; // Switch here to run process
   struct trapframe *tf; // Trap frame for the
                 // current interrupt
};
```

# How Is Kernel and User Code Execution Interleaved?

- Principle of OSes: the same physical core runs both kernel and user (process) code
- User code runs at full CPU speed
- But kernel maintains control

# How???

## **Example Execution**

OS	Program
<ol> <li>Create entry for process list</li> <li>Allocate memory for program</li> <li>Load program into memory</li> <li>Set up stack with argc / argv</li> <li>Clear registers</li> <li>Execute call main ()</li> </ol>	
	7. Run main() 8 Execute return from main()
9. Free memory of process 10. Remove from process list	

• But the OS is the boss of all resources, not just a library, so how does it take back control?

# System Calls, Interrupts

- User vs. Kernel CPU mode
  - not all programs can do everything
- System calls for all resource access
  - trap, return-from-trap instructions
  - "trap" = synchronous, user-initiated interrupt

OS @ run (kernel mode)	Hardware	Program (user mode)
initialize trap table	remember address of syscall handler	
Create process structs Load program into memory Setup user stack with argv Fill kernel stack with reg/PC <b>return-from -trap</b>		
	restore regs move to user mode jump to main	Run main()  Call system
Handle trap Do work of syscall <b>return-from-trap</b>	save regs to kernel stack move to kernel mode jump to trap handler	trap into OS
•	restore regs move to user mode jump to PC after trap	

# Is This Enough?

- What if a process is stuck in infinite loop?
  - historical note: cooperative multiprocessing
- Hardware again to the rescue!
  - OS has set a timer interrupt
  - a process only runs for a *time slice*
  - scheduling decision afterwards
  - context switch if needed

# xv6 (old) Context Switch Code

```
1 # void swtch(struct context *old, struct context *new);
2 #
3 # Save current register context in old
4 # and then load register context from new.
5 .globl swtch
6 swtch:
    # Save old registers
7
    movl 4(%esp), %eax
                             # put old ptr into eax
8
9
   popl 0(%eax)
                              # save the old IP, stack contents: return,old,new
10
  movl %esp, 4(%eax)
                             # and stack
11
  movl %ebx, 8(%eax)
                              # and other registers
12
   movl %ecx, 12(%eax)
13
   movl %edx, 16(%eax)
    movl %esi, 20(%eax)
14
    movl %edi, 24(%eax)
15
16
    movl %ebp, 28(%eax)
17
18
    # Load new registers
19
    movl 4(%esp), %eax
                              # put new ptr into eax, was 8(%esp) but popped return
20
    movl 28(%eax), %ebp
                              # restore other registers
21
    movl 24(%eax), %edi
2.2
    movl 20(%eax), %esi
23
    movl 16(%eax), %edx
24
    movl 12(%eax), %ecx
25
    movl 8(%eax), %ebx
26
    movl 4(%eax), %esp
                              # stack is switched here
27
     pushl 0(%eax)
                         # return addr put in place
2.8
                    # finally return into new ctxt
     ret
```

# What If Interrupted During Interrupt Handling?

- OS can briefly disable interrupts
- ... or ensures safe access to data structures through concurrency control mechanisms (e.g., locking)